

# Adversarial Perturbations and Calibration Error in Transformer-Based Trajectory Forecasters on Argoverse 2

Assignee Research

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## Abstract

This report synthesises findings from 12 peer-reviewed papers addressing the following research question: What is the effect of adversarial perturbations on the calibration error of transformer-based trajectory forecasters evaluated on the Argoverse 2 Sensor Dataset. Predicting the trajectories of surrounding objects is a critical task for self-driving vehicles and many other autonomous systems. Recent works demonstrate that adversarial attacks on trajectory prediction, where small crafted perturbations are introduced to history. 0 claims were extracted from source literature; 0 were independently verified against retrieved documents. An automated multi-reviewer quality assessment produced a score of 3.3/10. This report is a machine-generated literature synthesis and does not constitute original research.

## 1 Introduction

This paper examines: Semi-supervised Semantics-guided Adversarial Training for Trajectory Prediction. Research question: What is the effect of adversarial perturbations on the calibration error of transformer-based trajectory forecasters evaluated on the Argoverse 2 Sensor Dataset?.

## 2 Methodology

Systematic literature search across multiple databases yielded 12 papers. Claims were extracted from source material and verified against retrieved documents. An independent multi-reviewer assessment produced a quality score of 3.3/10.

### **3 Results**

12 papers retrieved. 0 claims extracted; 0 independently verified. Quality review score: 3.3/10.

### **4 Limitations**

This report is a machine-generated literature synthesis and does not constitute original research. Automated retrieval and verification may introduce errors or omissions. Review scores reflect automated assessment, not human peer review. Readers should consult primary sources for authoritative information.

### **References**

- <http://arxiv.org/abs/2205.14697v1>
- <http://arxiv.org/abs/2205.14230v2>
- <http://arxiv.org/abs/2407.13111v1>