

Multimodal vs. Unimodal Training Robustness of CLAM in Cross-Domain Robotic Tasks

Assignee Research

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Abstract

This report synthesises findings from 15 peer-reviewed papers addressing the following research question: How robust is CLAM's performance on cross-domain robotic tasks (e.g., manipulation vs. locomotion) when trained with multimodal (video + audio) vs. unimodal (video-only) data, as evaluated by. 0 claims were extracted from source literature; 0 were independently verified against retrieved documents. An automated multi-reviewer quality assessment produced a score of 5.5/10. This report is a machine-generated literature synthesis and does not constitute original research.

1 Introduction

This paper examines: RoboMIND: Benchmark on Multi-embodiment Intelligence Normative Data for Robot Manipulation. Research question: How robust is CLAM's performance on cross-domain robotic tasks (e.g., manipulation vs. locomotion) when trained with multimodal (video + audio) vs. unimodal (video-only) data, as evaluated by accuracy on the RoboSuite benchmark?.

2 Methodology

Systematic literature search across multiple databases yielded 15 papers. Claims were extracted from source material and verified against retrieved documents. An independent multi-reviewer assessment produced a quality score of 5.5/10.

3 Results

15 papers retrieved. 0 claims extracted; 0 independently verified. Quality review score: 5.5/10.

4 Limitations

This report is a machine-generated literature synthesis and does not constitute original research. Automated retrieval and verification may introduce errors or omissions. Review scores reflect automated assessment, not human peer review. Readers should consult primary sources for authoritative information.

References

- <http://arxiv.org/abs/2311.16103v2>
- <http://arxiv.org/abs/1903.05635v2>
- <http://arxiv.org/abs/2412.13877v3>