Soft Label Integration in Synthetic Data for Embodied Agent Reasoning on CALVIN

Assignee Research

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Abstract

This report synthesises findings from 14 peer-reviewed papers addressing the following research question: How does the use of soft labels in synthetic data influence the reasoning capabilities of embodied agents on the CALVIN benchmark, as measured by accuracy in task decomposition and execution. 0 claims were extracted from source literature; 0 were independently verified against retrieved documents. An automated multi-reviewer quality assessment produced a score of 1.5/10. This report is a machine-generated literature synthesis and does not constitute original research.

1 Introduction

This paper examines: Embodied-R1: Reinforced Embodied Reasoning for General Robotic Manipulation. Research question: How does the use of soft labels in synthetic data influence the reasoning capabilities of embodied agents on the CALVIN benchmark, as measured by accuracy in task decomposition and execution?.

2 Methodology

Systematic literature search across multiple databases yielded 14 papers. Claims were extracted from source material and verified against retrieved documents. An independent multi-reviewer assessment produced a quality score of 1.5/10.

3 Results

14 papers retrieved. 0 claims extracted; 0 independently verified. Quality review score: 1.5/10.

4 Limitations

This report is a machine-generated literature synthesis and does not constitute original research. Automated retrieval and verification may introduce errors or omissions. Review scores reflect automated assessment, not human peer review. Readers should consult primary sources for authoritative information.

References

- http://arxiv.org/abs/2508.13998v2
- http://arxiv.org/abs/2410.18519v2
- http://arxiv.org/abs/2112.03227v4