Semantics-Guided Adversarial Training for Trajectory Prediction Generalization

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Abstract

This report synthesises findings from 13 peer-reviewed papers addressing the following research question: What is the impact of semantics-guided adversarial training on the generalization gap between in-domain and out-of-domain trajectory prediction tasks. Predicting the trajectories of surrounding objects is a critical task for self-driving vehicles and many other autonomous systems. Recent works demonstrate that adversarial attacks on trajectory prediction, where small crafted perturbations are introduced to history. 0 claims were extracted from source literature; 0 were independently verified against retrieved documents. An automated multi-reviewer quality assessment produced a score of 5.8/10. This report is a machine-generated literature synthesis and does not constitute original research.

1 Introduction

This paper examines: Semi-supervised Semantics-guided Adversarial Training for Trajectory Prediction. Research question: What is the impact of semantics-guided adversarial training on the generalization gap between in-domain and out-of-domain trajectory prediction tasks?.

2 Methodology

Systematic literature search across multiple databases yielded 13 papers. Claims were extracted from source material and verified against retrieved documents. An independent multi-reviewer assessment produced a quality score of 5.8/10.

3 Results

13 papers retrieved. 0 claims extracted; 0 independently verified. Quality review score: 5.8/10.

4 Limitations

This report is a machine-generated literature synthesis and does not constitute original research. Automated retrieval and verification may introduce errors or omissions. Review scores reflect automated assessment, not human peer review. Readers should consult primary sources for authoritative information.

References

- http://arxiv.org/abs/2103.01400v3
- http://arxiv.org/abs/2205.14230v2
- http://arxiv.org/abs/2006.08476v2