

Prompt Length and Task Accuracy in Embodied-R1 Versus Smaller VLA Models

Assignee Research

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Abstract

This report synthesises findings from 13 peer-reviewed papers addressing the following research question: What is the correlation between prompt length and task completion accuracy for Embodied-R1 compared to smaller VLA models in embodied navigation tasks. This paper develops LongNav-R1, an end-to-end multi-turn reinforcement learning (RL) framework designed to optimize Visual-Language-Action (VLA) models for long-horizon navigation. Unlike existing single-turn paradigm, LongNav-R1 reformulates the navigation decision process as a. 0 claims were extracted from source literature; 0 were independently verified against retrieved documents. An automated multi-reviewer quality assessment produced a score of 1.7/10. This report is a machine-generated literature synthesis and does not constitute original research.

1 Introduction

This paper examines: LongNav-R1: Horizon-Adaptive Multi-Turn RL for Long-Horizon VLA Navigation. Research question: What is the correlation between prompt length and task completion accuracy for Embodied-R1 compared to smaller VLA models in embodied navigation tasks?.

2 Methodology

Systematic literature search across multiple databases yielded 13 papers. Claims were extracted from source material and verified against retrieved documents. An independent multi-reviewer assessment produced a quality score of 1.7/10.

3 Results

13 papers retrieved. 0 claims extracted; 0 independently verified. Quality review score: 1.7/10.

4 Limitations

This report is a machine-generated literature synthesis and does not constitute original research. Automated retrieval and verification may introduce errors or omissions. Review scores reflect automated assessment, not human peer review. Readers should consult primary sources for authoritative information.

References

- <http://arxiv.org/abs/2508.13998v2>
- <http://arxiv.org/abs/2602.12351v1>
- <http://arxiv.org/abs/2603.14523v1>